

# Novel Mitigation and Monitoring of SSR Oscillations

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Papiya Dattaray - Cigre NGN 20/02/2018

### Outline 0

- ➢ Background
- Impact of Dynamic Loads on SSR
- ➢ Using Dynamic Loads to damp SSR
- ➢ What' s Next?
- ➢ Conclusions



#### A Brief Background to My Research

Part 1

## Fixed Series Compensation

 $\checkmark$  Higher power transfers,

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- $\checkmark$  Enhanced transient stability limits,
- $\checkmark$  Improved angular stability (reduced angular separation across corridors), and
- $\checkmark$  Self-regulatory and instantaneous VAr support (steady state & dynamic voltage stability)



## Fixed Series Compensation

- > Facilitate increased power transfer at a lower
  cost
- Great Britain increased flow of renewable generation from Scotland to England (B6) to help meet goal of 15% renewable energy by 2020:
  - Series capacitor banks have been installed at the Eccles, Moffat and Gretna substations (Scottish Power, 2015)
  - TCSC at the Hutton 400kV substation, near Kendal in Cumbria. Enhanced power transfer capacity by around 1 GW (National Grid, 2014)
  - Also installing HVDC in parallel to the AC network.

(National Grid, 2018)

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## Fixed Series Compensation

Facilitate increased power transfer at a lower cost

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Peterhead

#### Subsynchronous Interactions: A Definition

SSR is defined by IEEE as "the electrical power system condition where the electric network exchanges energy with a turbine generator at one or more of the natural frequencies of the combined system below the synchronous frequency of the system"

[Source: IEEE SSR Working Group, "Proposed Terms and Definitions for Subsynchronous Resonance", IEEE Symposium on Countermeasures for Subsynchronous Resonance, IEEE Pub. 81TH0086-9-PWR, 1981, p 92-97]



Shaft failure at Mohave (1970)



#### SSR: The Physics

- Natural frequencies occurring due to series capacitor compensation are below the nominal frequency of the network  $applied i(t) = K[Asin(w_1t + \psi_1) + Be^{-\varsigma w_2t}sin(w_2t + \psi_2)]$ 
  - w1 at the frequency of the driving voltage
  - w2 is dependant on the network parameter's
- $\succ$  Currents of frequency w2 are reflected onto the rotor as
  - Sum, (w1+w2) and difference (w1-w2) components
- Difference or subsynchronous component of current induces subsynchronous frequency shaft torque
  - Forque oscillations mean torsional stress and fatigue

#### Generator rotor as multi-mass

Mode zero represents the condition where the masses all move in phase and the entire shaft system behaves as a solid mass (Classical generator rotor model) with a common mode of oscillation



# Impact of dynamic loads on torsional interactions

Part 2

#### Load and SSR: EMT Studies

- Generation station modelled in detail
  - turbines, generators, speed governors, excitation systems
- Network is modelled in detail using algebraic and ordinary differential equations

But impact of LOADS is either neglected (IEEE Benchmark models) or assumed as constant Impedance (STATIC) models (throughout the years of SSR research)

- The impact of loads on system dynamics has been widely investigated for the classical stability studies but not for torsional interactions
- Load modelling for assessment of SSR becomes critically important when the load center is in close electrical proximity to a generation center

In the absence of appropriate load models, simulations may over or underestimate the risk of SSR, which may cause the protection or mitigation to be over/ under-designed

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#### Loads and SSR Damping



#### Aggregation of loads at the transmission level

Table I. List of load types considered

Load Type	Description
Type 1	Loads neglected
Type 2	100% Const. Impedance
Туре З	50% DOL and 50% VFD based Motor loads
Type 4	100% DOL connected Motor load
Туре 5	30% Const. Impedance 30% Const. Current 40% DOL connected Motor load
Туре б	50% Constant Impedance 50% DOL connected

unstable for Type 1 and 2 Time (sec) stable for Types 3, 4, 5 and 6

#### **Conservative results impact decisions**

•at the planning stage

(regarding location and/or degree of compensation)

• during operation (setting improper thresholds for online alarms against dangerous interactions).

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#### Do Loads Interact with SSR?







#### Novel SSR Mitigation - Auxiliary damping controller

Part 3

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#### Protection Vs. Mitigation

**Protection** involves forced tripping (removal of generator or series capacitor), which is disruptive for a system that is already in a weakened state due to outages and is generally *recommended as a backup means of defence*.





*Mitigation* involves reducing the exposure of the system to the risk of SSR and thus allowing the vulnerable resources to continue operating, even when outages result in stronger electrical coupling between a generator and a series capacitor. In many cases, mitigation may also be able to completely eliminate the risk of SSR.

#### Traditional means for Managing SSR

It is essential to *detect instability* in the subsynchronous modes of vibration and to do this *as fast as possible* and evaluate the need to take proactive action.



## Proposed Control Solution

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- The proposed ADC uses the existing auxiliary power plant 11 kV VFD interfaced induction motor loads (e.g FD/ID Fans and pump loads) that are available locally right at the generation centre
- The ADC exploits their speed control systems with minor modifications to the control loop, which incurs little to no additional costs and ensures easy deployment
- It uses the turbine output power as the control system input, which is a standard power plant control room signal and does not need additional communication or dedicated monitoring

## Residue based ADC design



Three-phase controller diagram for the VFD\_AD

# VFD based auxiliary power plant loads

The most important power plant auxiliary loads with variable frequency drives (VFDs) are Boiler Feed Water pumps (BFWs), Induced Draft (ID) fans and Forced Draft (FD) fans

Significant Capacity

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- $\succ$  3.6 % in fans and 7.2 % in pumps of the plant generation capacity
- FD and ID fans, used in power plant combustion processes consume significant amounts of power with motor sizes approaching 14 to 18 MW in many large power plants.

#### High availability and redundancy

Additional pumps/fans available as backup or two pumps/fans operating in parallel at 50 % of their capacity

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## Performance Evaluation: Test Systems

#### IEEE First Benchmark



#### IEEE 68 Bus System

- VFD with ADC control added to two test systems
- Lines removed in 68 bus system
  - to leave generator radial to SC
- The ADC stabilised the SSR



Performance Evaluation: FFT Analysis



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## Testing for different modes: 25 and 32



(a) turbine output power (b) unstable SSR in turbine shaft section speeds (c) turbine shaft section speeds in the presence of VFD motor (d) stable shaft speed oscillations with ADC (e) Frequency spectrum seen in turbine output power with VFD-AD (f) FFT amplitude spectrum for Pt from 13-14.5 sec for No VFD and with VFD-AD

## Testing for different modes: 25 and 32





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### ADC performance for TA

ADC effective against Torque SSR-LI shown through motor electrical Amplification torque versus speed plot Three phase short circuit in IEEE FBM (a) no ssr damper (b) zoom of plot (a) of fault times 0.9 1.5 Toctod range Wh Fault Torque(p.u.) 0.8 Torque(p.u.) Cases clearing ς 1 a a times 0.984 0.026 0.02 0.026 5ms 0.5 0.75 10ms 1.072 0.024 0.022 0.024 0.996 0.998 1 1.002 0.9998 1.0002 0.994 1.0004 0.864 0.026 0.017 0.026 Speed(p.u.) Speed(p.u.) 20ms No ADC (c) with ssr damper (d) zoom of plot (c) 40ms 0.454 0.026 0.009 0.026 1.2 0.9 0.027 0.013 0.027 50ms 0.661 Torque(p.u.) 0.0 0.0 Torque(p.u.) 0.8 83.3ms 0.0230.002 0.13 0.023 -0.208 -0.21 1.712 0.035 5<sub>ms</sub> 1.922 -0.2170.037 -0.21410 ms0.75 0.4 1.574 -0.222 0.032 -0.219 With 20ms 0.994 0.996 0.998 1.002 0.9998 1.0002 1 1 1.0004 Speed(p.u.) Speed(p.u.) ADC 0.821 -0.215 0.016 -0.211 40ms 1.198 -0.216 0.024 -0.213 50ms 83.3ms 0.243 -0.217 0.004 -0.204 Dual protection for both the generator and vital auxiliaries

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#### Challenges identified ....

- The effectiveness of the ADC and participation of the VFD based motor load in SSR damping would depend on its loading at the time of the disturbance
- When the VFD is operating at, or close to, its full load capacity the proposed ADC will not be able to provide satisfactory damping
- Simplistic control method adopted by the proposed ADC must be tuned for a specific shaft mode
- Future work will involve looking at robust control designs that may damp multiple torsional modes simultaneously.

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#### Conclusions and Future Work

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- ➤ The ADC performance is evaluated for both TI and TA types of SSR interactions in the IEEE FBM and IEEE 68 bus networks and is shown to provide effective positive damping and mitigate SSR under a range of operating conditions
- The solution is novel and practical and it incurs minimum additional costs by virtue of exploiting existing resources and provides an effective means for SSR mitigation right at the point of vulnerability (generation centre)
- ➢ A rather simplistic control architecture has been adopted here to provide a proof of concept.



#### Thank you, any questions?

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